

Faculty Name:

Matei Ciocarlie

Faculty Email:

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Lab:

ROAM

Project Title:

A Teleoperation Framework for Dexterous Robot Hands

Description:

Develop a framework for teleoperating novel dexterous robotic hands in a simulated environment, with the goal of performing design optimization and Behavioral Cloning on the resulting models.

Location of Research:

On Site

of hrs/week:

40

Department/Program:

Mechanical Engineering

Eligibility:

BS, Second Year

To apply, please contact:

Matei Ciocarlie

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