Faculty Name:
Matei Ciocarlie

Faculty Email:
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Lab:
ROAM

Project Title:
A Teleoperation Framework for Dexterous Robot Hands

Description:
Develop a framework for teleoperating novel dexterous robotic hands in a simulated environment, with the goal of performing design optimization and Behavioral Cloning on the resulting models.

Location of Research:
On Site

# of hrs/week:
40

Department/Program:
Mechanical Engineering

Eligibility:
BS, Second Year

To apply, please contact:
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